

Smart Mobility Readiness Forum

Municipal Incident Reporting Using Artificial Intelligence



Established Company - Visual Defence



Headquartered in Richmond Hill, Ontario, Canada 🌞

20 Years in Business

Focused on Security, AI, and Mobility Applications (Thanks to AVIN)

Extensive presence in the transportation sector



Collaboration with CRH & Others























and the ROVER Workgroup



What is the ROVER Workgroup?

The ROVER workgroup, initiated by Visual Defence Inc. and the City of Richmond Hill is a collection of organizations and municipalities who seek to investigate how artificial intelligence could be used for the betterment and safety of Canada's road network.

What does the workgroup do for you?



We value your feedback

Be involved in building the solution you want to see. ROVER will be tailored to meet the needs of road operations. We want to fine tune only the features that matter to you



Networking opportunity

Opportunity to learn road maintenance strategies from other municipalities and organizations



Positive Exposure

Be a part of a new and exciting way to improve Canadian road safety



"We are excited to partner with Richmond Hill's own Visual Defence to test the Rover technology. This type of collaboration and innovation is crucial for moving municipalities forward."

Matt Mintz

Manager of Road Operations



"The City of Markham supports the development of technologies aimed at helping Canadian municipalities improve and maintain their road networks."

Senior Manager of Roads, Survey & Utility



AURORA

"We are looking forward to testing Rover to see how it can create efficiencies in reducing the amount of staff hours that go into documenting and creating work orders for potholes."

Dan Naccarato

Supervisor of Roads & Traffic



New Tecumseth

"New Tecumseth is excited to test Rover and see how it can create efficiency in road patrol and other areas of our business."

Chris Trombino

Manager of Roads and Fleet



"Technology that makes us more efficient and that leads to a better user experience on our roads is what Innisfil is looking for. We're looking forward to seeing how the Rover technology performs"

Brian Seed

Manager of Road Operations

East "We are e

East Gwillimbury

"We are excited to participate in this technology pilot to provide the Town of East Gwillimbury with another tool in our arsenal to help identify pothole locations, expedite tracking and repair all with the objective of providing a safer municipal road network"

Jeff Meggitt

Manager of Operations

The World's Largest Collaborative R&D Project, aimed at improving road conditions





What is ROVER



- ROVER is an app that is installed on a smartphone.
- ROVER automatically identifies
 potholes on the road using artificial intelligence and maps them.





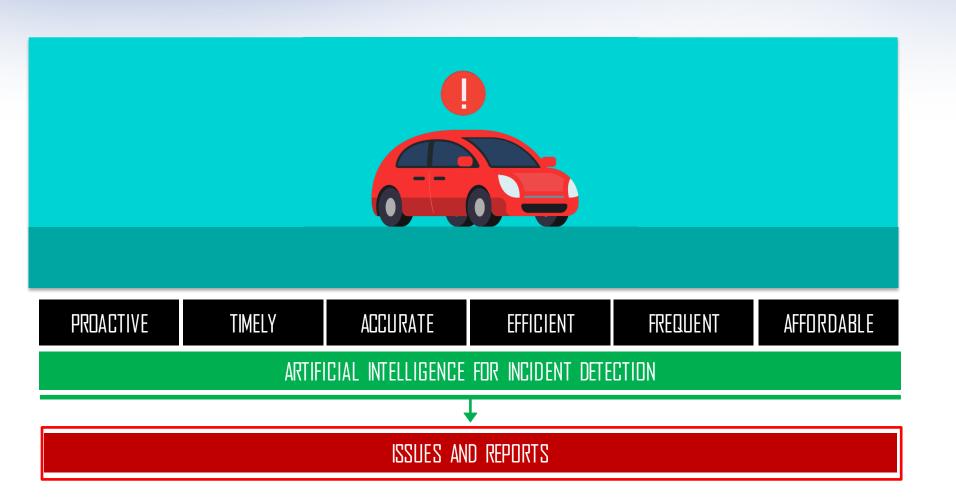




Automated Pothole Detection Using Artificial Intelligence

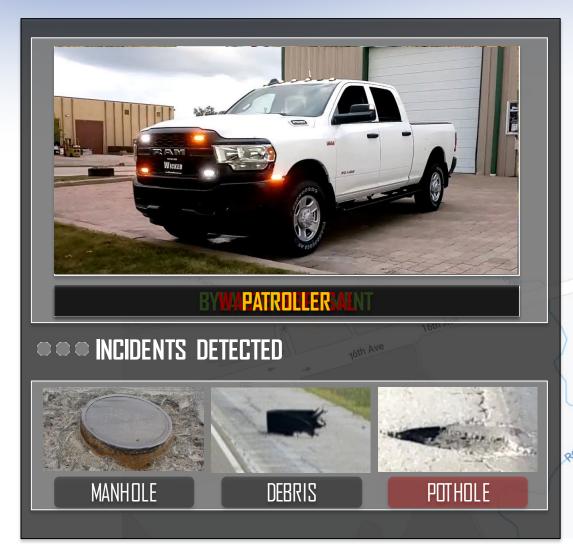
Why use ROVER?

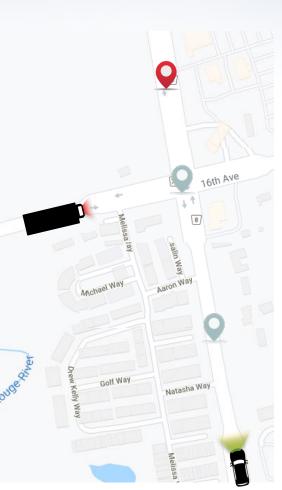




The Future: ROVER SmartFleets







Challenges





- Change
- Trust
- Technological
- Procedural
- Capacity
- Buy-in

Opportunities





- Chance to improve
- Influence roadmap
- Collective power
- Quantify impact
- Share knowledge
- Showcase our businesses

Thank You

Join the Collaboration ROY.TAL@VISUALDEFENCE.COM